(19) World Intellectual Property Organization

International Bureau





(43) International Publication Date27 January 2005 (27.01.2005)

PCT

(10) International Publication Number WO 2005/006939 A2

(51) International Patent Classification7:

A61B

(21) International Application Number:

PCT/US2004/019125

(22) International Filing Date: 14 Jun

14 June 2004 (14.06.2004)

(25) Filing Language:

English

(26) Publication Language:

English

(30) Priority Data:

60/478,041 11 June 2003 (11.06.2003) US 60/478,662 13 June 2003 (13.06.2003) US 60/478,692 13 June 2003 (13.06.2003) US 60/483,324 27 June 2003 (27.06.2003) US

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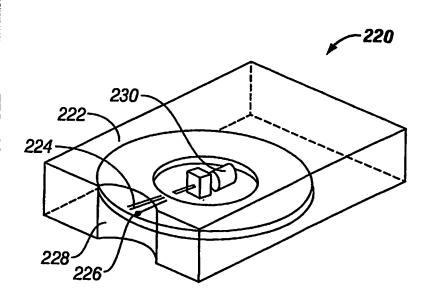
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- (81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BW, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NA, NI, NO, NZ, OM, PG, PH, PL, PT, RO, RU, SC, SD, SE, SG, SK, SL, SY, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, YU, ZA, ZM, ZW.
- (84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IT, LU, MC, NL, PL, PT, RO, SE, SI, SK, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Published:

 without international search report and to be republished upon receipt of that report

For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.

(54) Title: METHOD AND APPARATUS FOR BODY FLUID SAMPLING AND ANALYTE SENSING



(57) Abstract: A method of controlling a penetrating member is provided. The method comprises providing a lancing device comprising a penetrating member driver having a position sensor and a processor that can determine the relative position and velocity of the penetrating member based on measuring relative position of the penetrating member with respect to time; providing a predetermined velocity control trajectory based on a model of the driver and a model of tissue to be contacted. In some embodiments, feedforward control to maintain penetrating member velocity along said trajectory.

(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(19) World Intellectual Property Organization

International Bureau





(43) International Publication Date 27 January 2005 (27.01.2005)

PCT

(10) International Publication Number WO 2005/006939 A3

(51) International Patent Classification7: A61B 5/00, B65D 33/00, 81/00

(21) International Application Number:

PCT/US2004/019125

(22) International Filing Date: 14 June 2004 (14.06.2004)

(25) Filing Language:

English

(26) Publication Language:

English

(30) Priority Data:

60/478,041 11 June 2003 (11.06.2003) US 60/478,662 13 June 2003 (13.06.2003) US 60/478,692 13 June 2003 (13.06.2003) US 60/483,324 27 June 2003 (27.06.2003) US

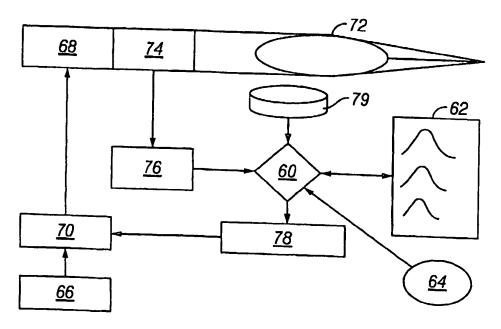
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(54) Title: METHOD AND APPARATUS FOR BODY FLUID SAMPLING AND ANALYTE SENSING



(57) Abstract: The method comprises providing a lancing device comprising a penetrating member (68) driver having a position sensor (74) and a processor (60) that can determine the relative position and velocity of the penetrating member (18,72) based on measuring relative position of the penetrating member with respect to time; providing a predetermined velocity control trajectory based on a model of the driver (68) and a model of tissue to be contacted. Furthermore, a feedforward control is able to maintain penetrating member velocity along the trajectory.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IT, LU, MC, NL, PL, PT, RO, SE, SI, SK, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Published:

with international search report

- before the expiration of the time limit for amending the claims and to be republished in the event of receipt of amendments
- (88) Date of publication of the international search report: 31 March 2005

For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.